

Programming Language Semantics and Compiler Design (Sémantique des Langages de Programmation et Compilation)

Types and Type Analysis

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Outline - Types and Type Analysis

Types in Programming Languages

How to Formalize a Type System?

Type system for the While language and its extensions

Type System for other language features

Some Implementation Issues

Conclusion

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What is a type?

- ▶ It defines the set of **values** an expression can take at run-time.
- ▶ It defines the set of **operations** that can be applied to an identifier.
- ▶ It defines the **resulting type** of an expression after applying an operation.

Objectives:

- ▶ prevent runtime errors;
- ▶ anticipate the runtime behavior.

Example 1 (Types)

int, float, unsigned int, signed int, string, array, list, ...

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What are Types Useful for?

Types and Type Analysis

Types and Type Analysis

Example 2 (Program readability)

```
var e : energy := ... ; -- partition over the variables
var m : mass := ... ;
var v : speed := ... ;
e := 0.5 * (m*v*v) ;
```

Example 3 (Program correctness)

```
var x : kilometers ;
var y : miles ;
x := x + y ; -- typing error
```

Example 4 (Program optimization)

```
var x1, y1, z1 : integer ;
var x2, y2, z2 : real ;
x1 := y1 + z1 ; -- not the same representations and operators
x2 := y2 + z2 ;
```

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Type Safety

Types and Type Analysis

Types and Type Analysis

'Well-typed programs never go wrong...'

(Robin Milner)

Trapped errors vs untrapped errors.

- ▶ trapped errors cause computation to stop immediately (e.g., division by 0, access to an illegal address);
- ▶ untrapped errors may go unnoticed (e.g., access to a non valid address).

Type safety

A well-typed program never executes "out-of-semantics" behaviors

⇒ NO meaningless well-typed programs
 (no untrapped errors, no undefined behaviors)

Example 7

Type safe languages

- ▶ C, C++ are **(definitely!) not type safe**
- ▶ ML, Rust are type safe
- ▶ Java, C#, Python, OCaml are **"considered as"** type safe

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Typed and Untyped Languages

Types and Type Analysis

Definition 1 (Typed languages)

A **dedicated** type is associated to each identifier (and hence to each expression).

Example 5 (Typed languages)

C, C++, Java, Ada, C, CAML, Rust, etc.

What about Python ? JavaScript ?? PHP ???

Remark **strongly** typed vs **weakly** typed languages... □

Definition 2 (Untyped languages)

A **single** (universal) type is associated to each identifier (and hence to each expression).

Example 6 (Untyped languages)

Assembly language, shell-script, Lisp, etc.

Definition 3 (Explicitly vs implicitly typed languages)

Explicitly typed when types are part of the syntax (implicitly typed otherwise).

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Types and type constructions

Types and Type Analysis

Basic types

integers, boolean, characters, etc.

Type constructions

- ▶ cartesian product (tuples, structures)
- ▶ disjoint union
- ▶ arrays
- ▶ functions
- ▶ pointers
- ▶ recursive types
- ▶ ...

But also:

subtyping, polymorphism, overloading, inheritance, coercion, overriding, etc.
 [see <http://luca-cardelli.name/Papers/OnUnderstandingA4.pdf>]

Subtyping

Subtyping is a preorder relation \leq_T between types.

It defines a notion of substitutability:

If $T_1 \leq_T T_2$,
then elements of type T_2 may be replaced with elements of type T_1 .

Example 8 (Sub-typing)

- ▶ class inheritance in OO languages ;
- ▶ Integer \leq_T Real (in several languages) ;
- ▶ Ada :


```
type Month is Integer range 1..12 ;
-- Month is a subtype of Integer
```

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Static checking vs dynamic checking

Static checking

Verification performed at compile-time.

Dynamic checking

Verification performed at run-time.

→ necessary to correctly handle:

- ▶ dynamic binding for variables or procedures
- ▶ polymorphism
- ▶ array bounds
- ▶ subtyping
- ▶ etc.

⇒ For most programming languages, both kinds of checks are used...

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Getting the Intuition on Examples

- ▶ "2 + 3 = 6" is well-typed
- ▶ "2 + true = false" is not well-typed
- ▶ "x = false" is well-typed
 if x is a (visible) Boolean variable
- ▶ "2 + x = y" is well-typed
 if x and y are (visible) integer/real variables
- ▶ "let x = 3 in x + y" is well-typed
 if y is a (visible) integer/real variable

⇒ a term t can be type-checked
under assumptions about its free variables ...

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Example: natural numbers

$$e := n \mid x \mid e_1 + e_2$$

Syntax

$$\frac{\Gamma(x) = \text{Nat}}{\Gamma \vdash x : \text{Nat}}$$

x is of type Nat in environment Γ if
 $\Gamma(x) = \text{Nat}$.

$$\frac{}{\Gamma \vdash n : \text{Nat}}$$

The denotation n is of type Nat.

$$\frac{\Gamma \vdash e_1 : \text{Nat} \quad \Gamma \vdash e_2 : \text{Nat}}{\Gamma \vdash e_1 + e_2 : \text{Nat}}$$

$e_1 + e_2$ is of type Nat assuming that e_1 and e_2 are of type Nat.

In a typed language, the set of "correct typing rules" is called the type system.

The static semantic analysis phase uses this type system in two ways:

Type checking

Check whether "type annotations" are used in a consistent way throughout the program.

Type inference

Compute a consistent type for each program fragment.

Remark In some languages (e.g., Haskell, CAML), there are/can be no type annotations at all (all types are/can be inferred). □

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How to Formalize a Type System?

- ▶ Abstract syntax describes terms (represented by ASTs).

- ▶ Environment Γ : Name $\xrightarrow{\text{part.}}$ Type.

- ▶ Judgment $\Gamma \vdash t : \tau$.
"In environment Γ , term t is well-typed and has type τ ."
(free variables of t belong to the domain of Γ)

- ▶ Type system

Inference rules	Axioms
$\frac{\Gamma_1 \vdash A_1 \quad \dots \quad \Gamma_n \vdash A_n}{\Gamma \vdash A}$	$\Gamma \vdash A$

Remark A type system is an inference system. □

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Derivations in a Type System

A type-check is a proof in the type system, i.e., a derivation tree where:

- ▶ leaves are axioms,
- ▶ nodes are obtained by application of inference rules.

A judgment is valid iff it is the root of a derivation tree.

Example 9

$$\frac{\emptyset \vdash 1 : \text{Nat} \quad \emptyset \vdash 2 : \text{Nat}}{\emptyset \vdash 1 + 2 : \text{Nat}}$$

Exercise

Prove that $[x \rightarrow \text{Nat}, y \rightarrow \text{Nat}] \vdash x + 2 : \text{Nat}$.

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Expressions

Expressions: informal description

- ▶ same syntax for Boolean and integer expressions (e).
- ▶ 3 kinds of (syntactically) distinct binary operators:
 arithmetic (opa), boolean (opb) and relational (oprel)
- ▶ (The following can be easily extended to account for unary operators over integers and booleans.)

Expressions: abstract grammar

$$e ::= \text{true} \mid \text{false} \mid n \mid x \mid e \text{ opa } e \mid e \text{ oprel } e \mid e \text{ opb } e$$

where **true** and **false** are the boolean constants, n denotes a natural number, and x denotes a variable.

Expressions

Let us consider opa to be $\{+, -, \times, \dots\}$, opb to be $\{\text{and}, \text{or}, \dots\}$, and oprel to be $\{=, <, >, \neq, \dots\}$. For example:

- ▶ 42
- ▶ x_1
- ▶ $2 \times x_2$
- ▶ $x_1 = x_2$
- ▶ false
- ▶ $x_1 + 42$
- ▶ x_b and $x_2 > 0$
- ▶ $x_1 > x_2$

are expressions obtained with the above grammar.

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- ▶ $\Gamma \vdash S$

"In environment Γ , statement S is well-typed".

- ▶ $\Gamma \vdash e : t$

"In environment Γ , expression e is of type t ".

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Assignment	Skip
$\Gamma \vdash e : t \quad \Gamma \vdash x : t$ $\Gamma \vdash x := e$	$\Gamma \vdash \text{skip}$

Sequence	Iteration
$\Gamma \vdash S_1 \quad \Gamma \vdash S_2$ $\Gamma \vdash S_1; S_2$	$\Gamma \vdash e : \text{Bool} \quad \Gamma \vdash S$ $\Gamma \vdash \text{while } e \text{ do } S \text{ od}$

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Statements

$S ::=$	$x := e$	(assignment of an expression to a variable x)
	skip	(doing nothing)
	$ S ; S$	(sequential composition)
	$ \text{if } e \text{ then } S \text{ else } S \text{ fi}$	(conditional composition)
	$ \text{while } e \text{ do } S \text{ od}$	(iterative and unbounded composition)

Statements

Assume a set of variable names x, x_1, y, z . For example:

skip	$x_1 := 42 + y;$...
	if $(x_1 + z > 0)$ then	...
$x_1 := 32$	$x_1 := 0;$	while $(x > 0)$ do
	$y := 42$	$y := y + z;$
	else	$x := x - 1$
	$x_1 := 42;$	od
$x_1 := 42;$	$y := 0$	
$y := x_1 + 12$	fi	

are statements obtained with the above grammar.

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bool. constant	int. constant	int opbin
$\Gamma \vdash \text{true} : \text{Bool}$	$\Gamma \vdash n : \text{Int}$	$\Gamma \vdash e_1 : \text{Int}$ $\Gamma \vdash e_2 : \text{Int}$
$\Gamma \vdash \text{false} : \text{Bool}$		$\Gamma \vdash e_1 \text{ opa } e_2 : \text{Int}$

variables	bool. opbin	relational operators
$\Gamma(x) = t$	$\Gamma \vdash e_1 : \text{Bool}$ $\Gamma \vdash e_2 : \text{Bool}$	$\Gamma \vdash e_1 : t$ $\Gamma \vdash e_2 : t$
$\Gamma \vdash x : t$	$\Gamma \vdash e_1 \text{ opb } e_2 : \text{Bool}$	$\Gamma \vdash e_1 \text{ oprel } e_2 : \text{Bool}$

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Exercise: conditional statement

Complete the type system by providing a rule for conditional statements.

Exercise: unary operators

Complete the abstract syntax and the type system by providing rules for unary operators.

Exercise: introducing reals and type conversion

Extend the type system for the expressions assuming that arithmetic types can be now either integer (**Int**) or real (**Real**).

Several solutions are possible:

1. Type conversions are never allowed.
2. Only explicit conversions (with a **cast** operator) are allowed.
3. (implicit) conversions are allowed.

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Definition 4 (Program abstract syntax)

The syntactic category **Prog** of programs (C, C', C_0, \dots) is defined as follows:

$$\begin{aligned} C &::= \text{global } D_V \text{ in } S \\ D_V &::= x : t, D_V | \varepsilon \end{aligned}$$

where:

- $D_V = x_1 : t_1, \dots, x_n : t_n$ ($n \geq 0$) are the **global variables**, where:
 $x_i : t_i \in \text{Var} \times \text{Type}$ declares a variable x_i of type t_i
 (see later for other forms of variable declarations).
- S is the **program body**.

Example 10 (Program)

The following program initializes x and y and then swaps their values:

```
global x:Int, y:Int, t:Int in
  x:=12; y:=42 ;
  t:=x ; x:=y ; y:=t
```

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Inference rule for programs

$$\frac{\emptyset \vdash D_V \mid \Gamma_g \quad \Gamma_g \vdash S}{\emptyset \vdash \text{global } D_V \text{ in } S}$$

Inference rules for declarations

$$\frac{\Gamma[x \mapsto t] \vdash D_V \mid \Gamma' \quad x \notin \text{vars}(D_V)}{\Gamma \vdash x : t ; D_V \mid \Gamma'}$$

$x \notin \text{vars}(D_V)$ prevents double variable declarations

Exercise: applying the typing rules

1. check that `global x:Int, y:Int in x:=1 ; y:=x+1` is well-typed.
2. check that `global x:Int, y:Int in x:=1 ; y:=z+1` is not well-typed.

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Type System for other language features**Some Implementation Issues****Conclusion**

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Definition 7 (Program abstract syntax)

The syntactic category **Prog** of programs (C, C', C_0, \dots) is defined as follows:

$$\begin{aligned} C &::= \text{global } D_V D_{Proc} \text{ in } S \\ D_V &::= x : t, D_V | \varepsilon \\ D_{Proc} &::= D_P, D_{Proc} | \varepsilon \end{aligned}$$

where:

- $D_V = x_1 : t_1, \dots, x_n : t_n$ ($n \geq 0$) are the **global variable declarations**
- $D_{Proc} = D_1, \dots, D_m \in \text{Pdef}$ ($m \geq 0$) are the **procedure declarations**.
- S is the **program body**.

Example 11 (Program)

The following program initializes x and y and then swaps their values:

```
global x:Int, y:Int in
  proc swap_x_y var t:Int in t:=x; x:=y; y:=t end
  x:=12; y:=42 ;
  swap_x_y
```

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Notations

- $\text{vars}(D_V)$ denotes the set of variables **declared** in D_V .
- $\Gamma[y \mapsto t]$ denotes the environment Γ' such that:
 - $\Gamma'(x) = \Gamma(x)$ if $x \neq y$
 - $\Gamma'(y) = t$

Judgments

- $\Gamma \vdash D_V \mid \Gamma$ means
 $\text{"declarations } D_V \text{ update environment } \Gamma \text{ into } \Gamma"$
- $\Gamma \vdash S$ means
 $\text{"statement } S \text{ is well-typed within environment } \Gamma"$
- $\Gamma \vdash C$ means
 $\text{"program } C \text{ is well-typed within environment } \Gamma"$

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Inference rules for declarations allowing re-declarations

$$\frac{\Gamma[x \mapsto t] \vdash D_V \mid \Gamma_i}{\Gamma \vdash x : t ; D_V \mid \Gamma_i}$$

gives priority to the last declarations.

Alternative declarations

- initialized variables: $x := e : t$
- untyped initialized variables: $x := e$
- uninitialized and untyped variables: x

We will study these alternatives during the tutorial ...

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Definition 5 (Syntactic categories of Proc)

- **Pid**: procedure identifiers (written F, F_0, F_1, \dots)
- **Pdef**: procedure definitions (written D, D_0, D_1, \dots)
- **Prog**: programs (written C, C_0, C_1, \dots)

Definition 6 (Syntax of procedure definitions)

The syntax of procedure definitions $D_P \in \text{Pdef}$ is as follows:

$$\begin{aligned} D_P &::= \text{proc } F \text{ is var } D_V \text{ in } S \text{ end} \\ D_V &::= x : t, D_V | \varepsilon \end{aligned}$$

where:

- $F \in \text{Pid}$ is the **procedure identifier**.
- $S \in \text{Stm}$ is the **procedure body**.
- $D_V = x_1 : t_1, \dots, x_n : t_n \in \text{Var} \times (n \geq 0)$ are the **local variable declarations**.
 If $n = 0$ then the keyword **var** may be omitted.

(Procedure parameters will be introduced later)

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- A **Procedure environment** is a (partial) function $\Gamma_P : \text{Pid} \rightarrow \{\text{proc}\}$

► $\text{procs}(D_P)$ denotes the set of procedures **declared** in D_P .

- For variable environments Γ_1 and Γ_2 , $\Gamma_1[\Gamma_2]$ denotes the environment Γ' such that:
 - $\Gamma'(x) = \Gamma_2(x)$ if $x \in \text{Dom}(\Gamma_2)$
 - $\Gamma'(x) = \Gamma_1(x)$ if $x \in \text{Dom}(\Gamma_1) \setminus \text{Dom}(\Gamma_2)$

- $\Gamma_V \vdash D_V \mid \Gamma'_V$ means

Variable declarations D_V update variable environment Γ_V into Γ'_V .

- $(\Gamma_V, \Gamma_P) \vdash D_P \mid \Gamma'_P$ means

Procedure declarations in D_P are well-typed within variable environment Γ_V and procedure environments Γ_P . Moreover, procedure declarations in D_P update procedure environment Γ_P into Γ'_P .

- $(\Gamma_V, \Gamma_P) \vdash S$ means

Statement S is well-typed within variable environment Γ_V and procedure environments Γ_P .

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Extending the Type System

Inference rule for programs

$$\frac{\emptyset \vdash D_V \mid \Gamma_g \quad (\Gamma_g, \emptyset) \vdash D_P \mid \Gamma_P \quad (\Gamma_g, \Gamma_P) \vdash S}{\emptyset \vdash \text{global } D_V \quad D_P \text{ in } S}$$

Inference rules for procedure declarations

$$(\Gamma_g, \Gamma_P) \vdash \epsilon \mid \Gamma_P$$

$$\frac{\emptyset \vdash D_V \mid \Gamma_I \quad (\Gamma_V, \Gamma_P) \vdash S \quad (\Gamma_g, \Gamma_P[F \mapsto \text{proc}]) \vdash D_P \mid \Gamma'_P \quad F \notin \text{procs}(D_P)}{(\Gamma_g, \Gamma_P) \vdash \text{proc } F \text{ is var } D_V \text{ in } S \text{ end ; } D_P \mid \Gamma'_P}$$

with $\Gamma_V = \Gamma_g[\Gamma_I]$, where local variables **hide** global ones ...

Inference rule for procedure calls

$$\frac{F \in \text{Dom}(\Gamma_P)}{(\Gamma_V, \Gamma_P) \vdash F}$$

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Exercise: playing with these inference rules ...

Type check the following programs:

C1

```
global x:Int, y:Int in
proc swap_x_y var t:Int in t:=x; x:=y; y:=t end
x:=12; y:=42;
swap_x_y
```

C2

```
global x:Int, y:Int, t:int in
proc swap_x_y var x:Int, y:Int in t:=x; x:=y; y:=t end
x:=true; y:=true;
swap_x_y
```

C3

```
global x:Bool, y:Bool in
proc swap_x_y var x:int, y:Int in t:=x; x:=y; y:=t end
x:=true; y:=true;
swap_x_y
```

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Procedures with parameters

Definition 8 (Updated Syntax of procedure definitions)

The syntax of procedure definitions $D_P \in \mathbf{Pdef}$ is as follows:

$$D_P ::= \text{proc } F(D_F) \text{ is var } D_V \text{ in } S \text{ end}$$

where:

$D_F = y_1 : t_1, \dots, y_n : t_n \in \mathbf{Var} \times \mathbf{Type}(n \geq 0)$ is the **formal parameters declaration**.

(if $n = 0$ then the parenthesis may be omitted)

Definition 9 (Updated Syntax of procedure calls)

$$S ::= \dots \mid F(e_1, \dots, e_n)$$

where **expressions** e_i are the **actual parameters**

Rk: we consider here **value-passing parameters**
(without distinguishing between **input/output** modes).

Example 12 (Procedure declaration)

```
proc max_z(a:Int, b:Int) is var m:Int in
  if (a>b) then m:=a else m:=b fi ; z:=m end
```

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Programs with procedures

Definition 10 (Program abstract syntax (unchanged))

The syntactic category **Prog** of programs (C, C', C_0, \dots) is defined as follows:

$$\begin{aligned} C &::= \text{global } D_V \quad D_{Proc} \text{ in } S \\ D_{Proc} &::= D_P, \quad D_{Proc} \mid \epsilon \\ D_V &::= x : t, \quad D_v \mid \epsilon \end{aligned}$$

where:

- $D_V = x_1 : t_1, \dots, x_n : t_n$ ($n \geq 0$) are the **global variable declarations**
- $D_{Proc} = D_1, \dots, D_m \in \mathbf{Pdef}$ ($m \geq 0$) are the **procedure declarations**.
- S is the **program body**.

Example 13 (Program)

```
global x:Int, y:Int, z:Int in
proc max_z(a:Int, b:Int) is var m:Int in
  if (a>b) then m:=a else m:=b fi ; z:=m end
x:=12; y:=42; max_z(x*4,y-1)
```

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Collisions between identifier names?

What to decide when a **same identifier** is used for a global variable, a formal parameter and a local variable ?

A syntactically correct program

```
global x:Int in
proc foo(x:Bool) is var x:Real in x:= ... end
...
```

From a **type-checking** viewpoint:

1. Is this program considered as correct?
2. What could be a valid right-hand side for the assignment of x within `foo`?

Proposed answers (compatible with NOS!):

possible collisions between global and local idfs, priority to local ones
possible collisions between variable and parameter idfs, priority to parameters.

Rk: collisions between procedure and variable/parameter idfs are **rejected**

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Extending (once again !) the Type System

A **Procedure environment** is now a (partial) function $\Gamma_P : \mathbf{Pid} \rightarrow (\mathbf{Type})^*$
mapping each procedure name to the **sequence** of its **formal parameter types**.
For a formal parameter declaration $D_F = (y_1 : t_1, \dots, y_n : t_n)$ we note
paramtypes(D_F) the sequence (t_1, \dots, t_n) .

Inference rules for procedure declarations

$$\frac{\emptyset \vdash D_F \mid \Gamma_F \quad \emptyset \vdash D_V \mid \Gamma_I \quad (\Gamma_V, \Gamma_P) \vdash S \quad (\Gamma_g, \Gamma_P[F \mapsto t_F]) \vdash D_P \mid \Gamma'_P \quad F \notin \text{procs}(D_P)}{(\Gamma_g, \Gamma_P) \vdash \text{proc } F(D_F) \text{ is var } D_V \text{ in } S \text{ end ; } D_P \mid \Gamma'_P}$$

where $t_F = \text{paramtypes}(D_F)$

where $\Gamma_V = (\Gamma_g[\Gamma_I])[t_F]$, meaning that parameters **hide** local/global variables ...

Inference rule for procedure calls

$$\frac{\Gamma_P(F) = (t_1, \dots, t_n) \quad \Gamma_V \vdash e_i : t_i}{(\Gamma_V, \Gamma_P) \vdash F(e_1, \dots, e_n)}$$

Rk: types of formal and actual parameters should agree **position-wise**

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Exercises

Applying the rules

Type check the two following programs:

```
global r:Int in
  proc add_r(x:Int, y:Int) is var s:Int in s:=x+y ; r:=s end
  x:=5; add_r(x,x+2)
```

```
global r:Int in
  proc foo (x:Int) is r:=x+1 ; foo(x)
  r:=5; foo(r)
```

Extensions and variants

- **recursive** procedure calls
- **mutually recursive** procedure calls
- **collateral** evaluation of procedure declarations
- **input/output** procedure parameters
- **functions** (extending the procedure declaration syntax)

→ Some of these extensions will be studied during the tutorials ...

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Outline: Types and Type Analysis

Types in Programming Languages

How to Formalize a Type System?

Type system for the While language and its extensions

Type System for other language features

Some Implementation Issues

Conclusion

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Syntax of the language

$$\begin{aligned} e &::= n \mid r \mid \text{true} \mid \text{false} \mid x \mid \text{fun } x : \tau . e \mid (e \ e) \mid (e , e) \\ \tau &::= \text{Bool} \mid \text{Int} \mid \text{Real} \mid \tau \rightarrow \tau \mid \tau \times \tau \end{aligned}$$

Example 14 (Programs)

- ▶ 42
- ▶ $(x \cdot 12.5)$
- ▶ (x , true)
- ▶ $\text{fun } x : \text{Bool}. x$
- ▶ $((\text{fun } x : \text{Bool}. x) \cdot 12)$
- ▶ $\text{fun } x : \text{Int} \rightarrow \text{Real}. (x \cdot 12)$

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We add a new construct:

$$\text{let } x = e_1 : \tau_1 \text{ in } e_2$$

Informal semantics:

within e_2 , each occurrence of x is replaced by e_1

Extending the type system to handle identifiers

$$\frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma[x \mapsto \tau_1] \vdash e_2 : \tau_2}{\Gamma \vdash \text{let } x = e_1 : \tau_1 \text{ in } e_2 : \tau_2}$$

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Expressions that can be typed:

- ▶ $((\text{fun } x.x) \cdot 1) : \text{Int}$
- ▶ $((\text{fun } x.x) \text{ true}) : \text{Bool}$
- ▶ $\text{let } x = 1 \text{ in } ((\text{fun } y.y) \cdot x) : \text{Int}$
- ▶ $\text{let } f = \text{fun } x.x \text{ in } (f \cdot 2) : \text{Int}$

Expressions that cannot be typed

$\not\exists (\Gamma, \tau)$ such that $\Gamma \vdash e : \tau$

- ▶ $(1 \cdot 2)$
- ▶ $\text{fun } x.(x \cdot x)$
- ▶ $\text{let } f = \text{fun } x.x \text{ in } ((f \cdot 1) , (f \text{ true}))$

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Definition 12 (Rules for system F)

$$\frac{\Gamma \vdash e : \tau \quad \alpha \notin \mathcal{D}(\Gamma)}{\Gamma \vdash e : \forall \alpha . \tau} \quad (\text{generalization})$$

$$\frac{\Gamma \vdash e : \forall \alpha . \tau}{\Gamma \vdash e : \tau[\tau' \mapsto \alpha]} \quad (\text{instanciation})$$

Example 16 (Programs)

- ▶ $\text{let } f = \text{fun } x.x \text{ in } ((f \cdot 1) , (f \text{ true}))$
- ▶ $\text{fun } x.(x \cdot x)$

Remark Type inference is no longer **decidable** in this type system... □

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Judgment

$\Gamma \vdash e : \tau$ means "In environment Γ , e is well-typed and of type τ ."

Type System

$$\frac{\Gamma \vdash n : \text{Int} \quad \Gamma \vdash r : \text{Real} \quad \Gamma \vdash \text{true} : \text{Bool} \quad \Gamma \vdash \text{false} : \text{Bool}}{\Gamma \vdash x : \Gamma(x)}$$

$$\frac{\Gamma[x \mapsto \tau_1] \vdash e : \tau_2}{\Gamma \vdash \text{fun } x : \tau_1. e : \tau_1 \mapsto \tau_2}$$

$$\frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma \vdash e_2 : \tau_2 \quad \Gamma \vdash e_1 : \tau_1 \mapsto \tau_2 \quad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash (e_1 , e_2) : \tau_1 \times \tau_2}$$

$$\frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash (e_1 e_2) : \tau_2}$$

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Syntax of the language

$$e ::= \dots \mid \text{fun } x.e \mid \text{let } x = e_1 \text{ in } e_2$$

Modified type system

$$\frac{\Gamma[x \mapsto \tau_1] \vdash e : \tau_2}{\Gamma \vdash \text{fun } x.e : \tau_1 \mapsto \tau_2}$$

$$\frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma[x \mapsto \tau_1] \vdash e_2 : \tau_2}{\Gamma \vdash \text{let } x = e_1 \text{ in } e_2 : \tau_2}$$

⇒ a unique value for type τ_1 has to be inferred ...

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We introduce:

- ▶ type variable α
- ▶ $\forall \alpha. \tau$ means " α can take any type within type expression τ "

Example 15 (Polymorphic expression)

$\text{fun } x.x$ is of type $\forall \alpha. \alpha \rightarrow \alpha$

Definition 11 (Set of free type variables)

Given an environment Γ :

$$\begin{aligned} \mathcal{D}(\text{Bool}) &= \mathcal{D}(\text{Int}) = \mathcal{D}(\text{Real}) = \emptyset \\ \mathcal{D}(\alpha) &= \{\alpha\} \\ \mathcal{D}(\tau_1 \rightarrow \tau_2) &= \mathcal{D}(\tau_1) \cup \mathcal{D}(\tau_2) \\ \mathcal{D}(\forall \alpha. \tau) &= \mathcal{D}(\tau) \setminus \{\alpha\} \\ \mathcal{D}(\Gamma) &= \bigcup_{x \in \text{dom}(\Gamma)} \mathcal{D}(\Gamma(x)) \end{aligned}$$

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Type quantifiers may only appear "in front" of type expressions.

Definition 13 (New Syntax)

$$\begin{aligned} \text{Types} \quad \tau &::= \text{Bool} \mid \text{Int} \mid \text{Real} \mid \tau \rightarrow \tau \mid \tau \times \tau \mid \alpha \\ \text{Type patterns} \quad \sigma &::= \tau \mid \forall \alpha. \sigma \end{aligned}$$

Definition 14 (New Rules for the Hindley-Milner system)

$$\frac{\Gamma \vdash e : \sigma \quad \alpha \notin \mathcal{D}(\Gamma)}{\Gamma \vdash e : \forall \alpha . \sigma} \quad (\text{generalization})$$

$$\frac{\Gamma \vdash e : \forall \alpha . \sigma}{\Gamma \vdash e : \sigma[\tau \mapsto \alpha]} \quad (\text{instanciation})$$

$$\frac{\Gamma \vdash e_1 : \sigma_1 \quad \Gamma[x \mapsto \sigma_1] \vdash e_2 : \sigma_2}{\Gamma \vdash \text{let } x = e_1 \text{ in } e_2 : \sigma_2} \quad (\text{polymorph "let"})$$

Example 17

$\text{let } f = \text{fun } x.x \text{ in } ((f \cdot 1) , (f \text{ true}))$

Beyond "pure" type checking ?

Some "typing rules" may not **strictly** concern types ...

Example: un-initialized variables in Java

each variable should be **defined** (i.e., **assigned**) before being **used** (\hookleftarrow **dataflow (def-use) relation**)

```
int x ;
int y ;
y = x+1 ; // ERROR: x is used before being assigned
```

Formalizing this rule with judgements ?

- Environment Γ is the set of **def** variables

$$\Gamma \subseteq 2^{\text{Name}} \quad (x \in \Gamma \text{ iff } x \text{ has been initialized})$$

- Judgment for Statement:

$$\Gamma \vdash S \mid \Gamma'$$

S is "well-typed" within Γ if it **uses** only variables in Γ and it produces a new environment Γ'

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Reminder

Several issues to be handled during static semantic analysis:

1. type-check the input AST

- formal specification = a **type system**
- notion of **environment** (name binding), to be computed:
 $\Gamma_V : \text{Name} \rightarrow \text{Type}$
 $\Gamma_P : \text{Name} \rightarrow \{\text{proc}\}$

2. decorate this AST to prepare code generation

- give a type to intermediate nodes
- indicate implicit **type conversions**

⇒ How to go from type system to algorithms?

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From a Type System to Algorithms?

⇒ recursive traversal of the AST...

AST representation:

```
typedef struct tnode {
    String string ; // lexical representation
    kind elem ; // category (idf, binaop, while, etc.)
    struct tnode *left, *right ; // children
    Type type ; // type (Int, Real, Void, Bad, etc.)
    ...
} Node ;
```

Type-checking function:

```
Type TypeCheck(* node) ;
// checks the correctness of node, returns the result Type
// and inserts type conversions when necessary
```

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Type Checking Algorithm for Statements

Sequence	Iteration	Assignment
$\Gamma \vdash S_1$	$\Gamma \vdash S_2$	$\Gamma \vdash e : \text{Bool}$
$\Gamma \vdash S_1, S_2$	$\Gamma \vdash e : \text{Bool}$	$\Gamma \vdash S$
	$\Gamma \vdash e : \text{Bool}$	$\Gamma \vdash e : t$
	$\Gamma \vdash \text{while } e \text{ do } S$	$\Gamma \vdash x : t$
		$\Gamma \vdash e : t$
		$\Gamma \vdash x := e$

```
function Type typeCheck(Node *node) {
switch node->elem {
case SEQUENCE:
if (typeCheck(node->left) != Void) return BAD ;
return typeCheck(node->right) ;
case WHILE:
if (typeCheck(node->left) != BOOL) return BAD ;
return typeCheck(node->right) ;
case ASSIGN:
Tl=typeCheck(node->left);
Tr=typeCheck(node->right);
if (Tl != Tr) return BAD else return VOID ;
}
}
```

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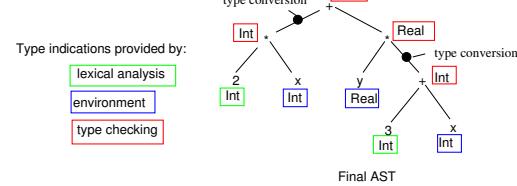
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Example

```
begin
var x : Int ;
var y : Real ;
y := 2 * x + y * (3 + x) ;
end
```



Final AST

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Type Checking Algorithm for Arithmetic Expressions

DENOT	BINAOP	IDF
$\Gamma \vdash n : \text{Int}$	$\Gamma \vdash e_l : T_l \quad \Gamma \vdash e_r : T_r \quad T = \text{resType}(T_l, T_r)$	$\Gamma(x) = t$
	$\Gamma \vdash e_l \text{ binaop } e_r : T$	$\Gamma \vdash x : t$

```
function Type typeCheck(Node *node) {
switch node->elem {
case DENOT: break ; // lexical analysis
case IDF: node->type=Gamma(node->string); break; // environment
case BINAOP: // type-checking
Tl=typeCheck(node->left);
Tr=typeCheck(node->right);
node->type=resType(Tl, Tr);
if (node->type != Tl) insConversion(node->left, node->type);
if (node->type != Tr) insConversion(node->right, node->type);
break ;
}
return node->type ;
}

function Type resType(Type t1, Type t2) {
if (t1==Boolean) or (t2==Boolean) return Bad; else return Max(t1, t2);
}
```

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Environment Implementation and Name Binding?

- Associate a type to each identifier

- each **use** occurrence \mapsto **decl** occurrence
- info should be retrieved efficiently (no AST traversal)

- distinguish between global/local variables, procedure names and formal parameters

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- ▶ Store all **information** associated to an identifier: type, kind (var, param, proc), address (for code gen), etc.
- ▶ Built during traversals of the **declaration parts** of the AST
- ▶ Efficient **search** procedure: binary tree, hash table, etc.
- ▶ Several solutions for handling **nested environment**, e.g., $(\Gamma_g[\Gamma_i])[\Gamma_f]$
 - ▶ a **global** table, with a **unique qualifying id** associated to each idf:
 $\{((x, \text{global}) : \text{Int}), ((x, \text{local}, \text{foo}) : \text{Real}), ((x, \text{param}, \text{foo}) : \text{Bool})\}$
 - ▶ a dynamic **stack of local tables**, one local table per environment, ordered by priority access, and updated at each procedure entry/exit
 $\{x: \text{Int}, \dots\} \rightarrow \{x: \text{Real}, \dots\} \rightarrow \{x: \text{Bool}, \dots\}$

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- ▶ Types are useful in programming languages:
 - ▶ to enforce **program correctness**
 - ▶ to ease program optimization
- ▶ Various type properties: **type safety**, weak vs strong type checking
- ▶ Typing rules can be (formally) specified using **type systems**
 - ▶ helps to verify the rule consistency, soundness & completeness
 - ▶ helps to **implement** the type-checker
- ▶ Type systems are also useful to specify/check **more general** program properties

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