Medical Imaging Simulation and Robotics

Introduction

Céline Fouard

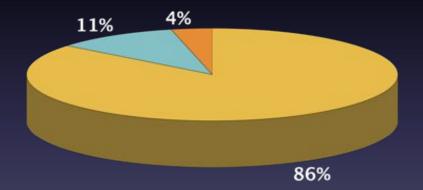
Jocelyne Troccaz

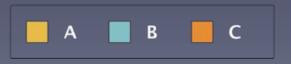
Emmanuel Promayon

CAMI Team TIMC-IMAG Laboratory

You follow this course from

- A. Master MoSIG
- B. Master PhysiqueMédicale
- C. Master MITI

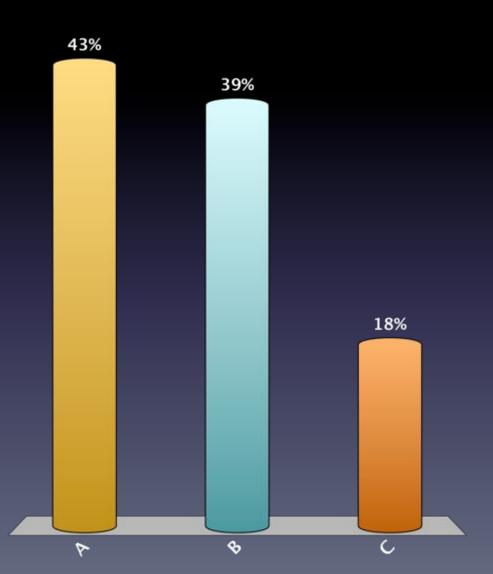




Your Professional Purpose is



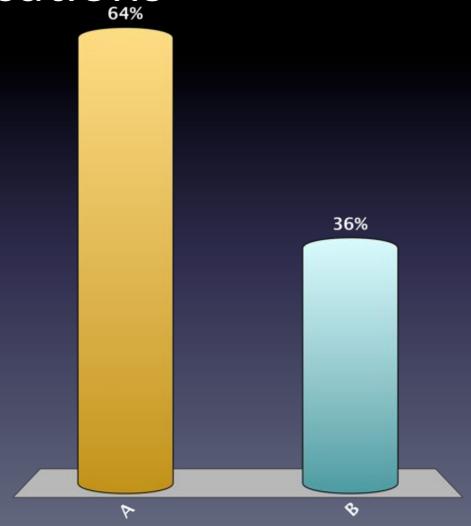
- B. Industry
- C. Medical Practice



You are interested in medical applications



B. False



Use Technology



Use Technology



Clinical Needs

- More and more
 - Efficiency
 - Security (patient, clinician)
 - Comfort
- Less and less
 - Pain
 - Invasivity
 - Hospital time spent
 - money

For you, What is the *Main* goal of Computer Assisted Medical Interventions?

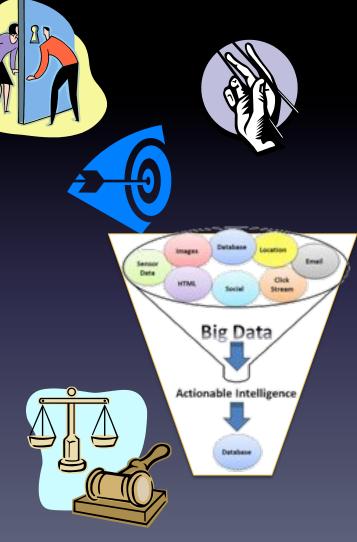
icia

7%

- A. More precise intervent ns
- B. More accurate interve on:
- C. More confort for the c
- D. Less expensive care
- E. Other

Today's medicine challenges

- Less invasivity
 - Less direct perception
 - Smaller targets
- More and more information
 - 2D, 3D, 4D, etc. images
- More and more legal criteria



Example of Challenge



75-711 = 40° T11-L4 = 320



A/P X-ray, patient standing up

COOB angles(after surgery): T11-L4 = 10°





Example of Challenge

- 10 to 40% of misplaced screws
 - Why is it so difficult?

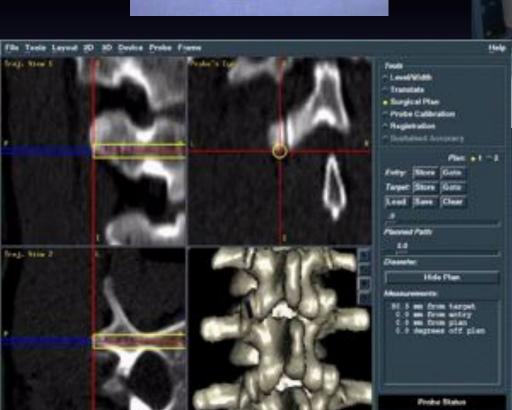
Example of Challenge



How can computers help?





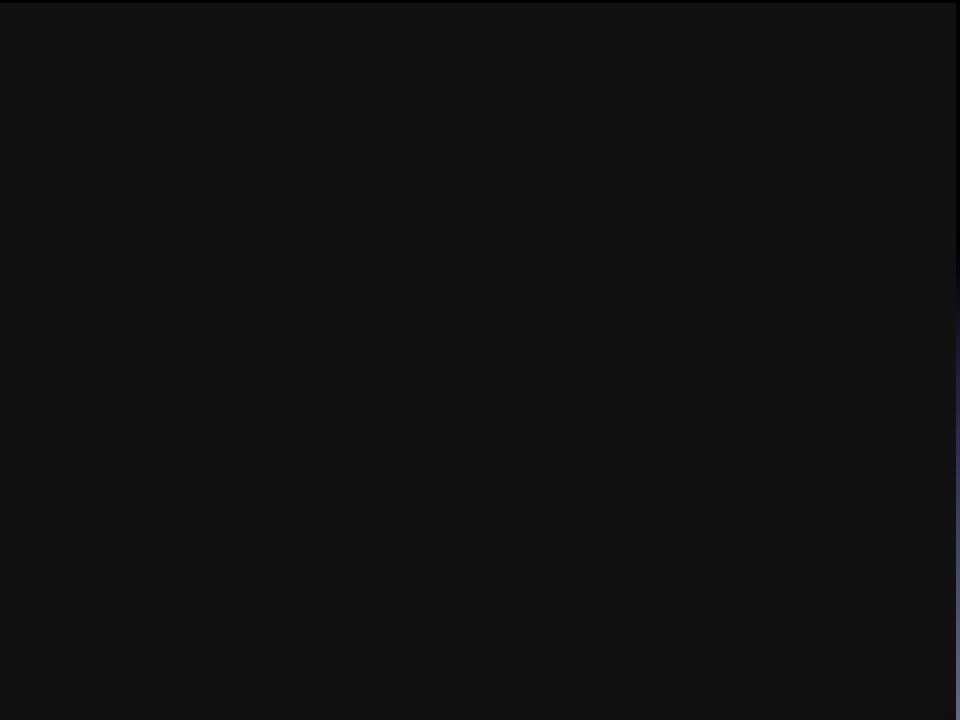


Frame Status



Video Example

- Note the elements of Navigation
- What is the map?
- What is the local frame?
- How to make them match?



Pre-operative Images are

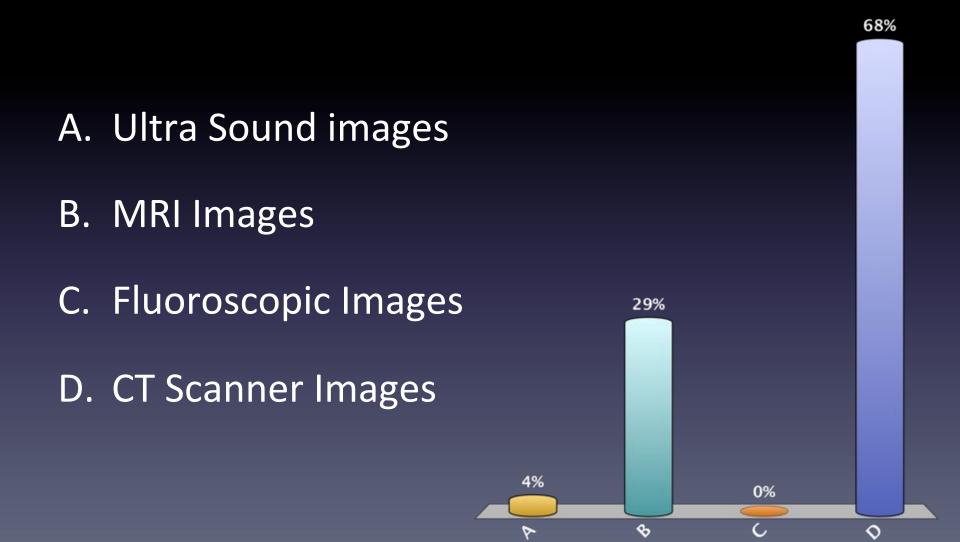


Image Processing Steps (Segmentation, 3D reconstruction, Adjusting zoon ontrast) are perfored

- A. Before the operation
- B. During the operation
- C. After the operation



Among the 3 per-operating references, which one is fixed

- A. The patient's head set
- B. The probe
- C. The tip of the instrumer



Among the 3 per-operating references, which one is used to match the patient's frar with the pre-operative im e?

11%

- A. The patient's headset
- B. The probe
- C. The tip of the instrument 11%













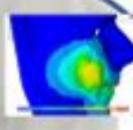


Sensing

Models



PERCEPTION





ACTION

REASONING





Robotics



Navigation



Simulation







Registration and data fusion

Course Organization

When	What	Who
01/10/2014	Introduction & Sensors	Céline Fouard
08/10/2014	Medical Imaging Part I	Céline Fouard
15/10/2014	Medical Imaging Part II	Céline Fouard
05/11/2014	Image Registration Part I	Jocelyne Troccaz
12/11/2014	Image Registration Part II	Jocelyne Troccaz
19/11/2014	Biomechanical Modeling Part I	Emmanuel Promayon
26/11/2014	Biomechanical Modeling Part II	Emmanuel Promayon
03/12/2014	No Lecture	
10/12/2014	Computer Exercise Part I	E. Promayon & C. Fouard
17/12/2014	CAMI Applications Part I & II	Jocelyne Troccaz
07/01/2015	Computer Exercise Part II	E. Promayon & C. Fouard